

Robust Discrete Optimization Under Ellipsoidal Uncertainty

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Context and positioning •OOOOOOO First heuristics

Second heuristics

Conclusions and perspectives

Need for robustness

Context





Context and positioning •OOOOOOO First heuristics

Second heuristics

Conclusions and perspectives





First heuristics

Second heuristics

Conclusions and perspectives





Context and positioning •OOOOOOO First heuristics

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Conclusions and perspectives



	Scenario 1	Scenario 2	Worst Scenario
$a \rightarrow b \rightarrow e$	50 min	9 min	50 min
$a \rightarrow c \rightarrow e$	21 min	23 min	23 min
$a \rightarrow d \rightarrow e$	12 min	48 min	48 min



Context and positioning OOOOOOO First heuristics

Second heuristics

Conclusions and perspectives





First heuristics

Second heuristics

Conclusions and perspectives

Need for robustness

Resulting facts

Uncertainty exists



First heuristics

Second heuristics

Conclusions and perspectives

Need for robustness

Resulting facts

Uncertainty exists Considering it is important



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Need for robustness

Resulting facts

Uncertainty exists
Uncertainty exists
Considering it is important
It makes problems harder

Optimal solutions are not valid



First heuristics

Second heuristics

Conclusions and perspectives

Uncertainty definition

Definition, cause, available information

Uncertainty= epistemic situation with unknown or imperfect information



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Conclusions and perspectives

Uncertainty definition

Definition, cause, available information

Uncertainty= *epistemic situation with unknown or imperfect information* It can be caused by future events, physical measurements that are already made, or the unknown



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Uncertainty definition

Definition, cause, available information

Uncertainty= epistemic situation with unknown or imperfect information It can be caused by future events, physical measurements that are already made, or the unknown

Available information or assumptions can exist: probability distribution, belonging to a set, information from the past, etc.



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Uncertainty definition

Definition, cause, available information

Uncertainty= epistemic situation with unknown or imperfect information
It can be caused by future events, physical measurements that are

already made, or the unknown

Available information or assumptions can exist: probability distribution, belonging to a set, information from the past, etc.

Uncertainty in an optimization problem:

 $\min_{x\in X_d}f(x,d),$

 X_d : feasible set under the realization d.



First heuristics

Second heuristics

Conclusions and perspectives

Chosen model of uncertainty

- Different approaches exist
- The choice of the approach is made for many reasons: how close to representing the reality, how easy the problem is to solve



First heuristics

Second heuristics

Conclusions and perspectives

Chosen model of uncertainty

Different definitions of worst case based approaches

Absolute robust decision



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Chosen model of uncertainty

Different definitions of worst case based approaches

Absolute robust decision

[Kouvelis et al. 2004, Buchheim and Kurtz 2018]

 $\min_{x\in X_d} f(x,d)$

$$z_A = \min_{x \in \cap_{d \in U} X_d} \max_{d \in U} f(x, d)$$

U is an uncertainty set Best in worst case, with cost=objective



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Chosen model of uncertainty

Different definitions of worst case based approaches

Absolute robust decision

Robust deviation decision



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Different definitions of worst case based approaches

Absolute robust decision decision

[Kouvelis et al. 2004, Buchheim and Kurtz 2018]

 $\min_{x\in X_d} f(x,d)$

$$Z_D = \min_{x \in \cap_{d \in U} X_d} \max_{d \in U} \left(f(x, d) - f(x_d^*, d) \right)$$

Best in worst case, with cost=deviation from optimal



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Chosen model of uncertainty

Different definitions of worst case based approaches

Absolute robust decision

Robust deviation decision

Relative robust decision



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Different definitions of worst case based approaches

 Absolute robust decision
 Robust deviation decision
 Relative robust decision

 [Kouvelis et al. 2004, Buchheim and Kurtz 2018]

$$z_R = \min_{\substack{x \in X_d \\ x \in \square_{d \in U} x_d}} \max_{\substack{d \in U}} \frac{f(x, d) - f(x_d^*, d)}{f(x_d^*, d)}$$

Best in worst case, with cost=relative deviation from optimal



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Different definitions of worst case based approaches

Absolute robust decision

Robust deviation decision

Relative robust decision



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Different definitions of worst case based approaches

Absolute robust decision

Robust deviation decision

Relative robust decision

Why absolute robust decision?

· Avoid to compute optimal solutions of all scenarios



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Chosen model of uncertainty

Different definitions of worst case based approaches

Absolute robust decision

Robust deviation decision

Relative robust decision

Uncertainty sets

Discrete set



First heuristics

Second heuristics

Conclusions and perspectives

Chosen model of uncertainty





First heuristics

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Chosen model of uncertainty

Absolute robust decision	Robust deviation decision	Relative robust decision
Uncertainty sets		
Discrete set	Interval set	



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Chosen model of uncertainty





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Absolute robust decision	Robust deviation decision	Relative robust decision
Uncertainty sets		
Discrete set	Interval set	Ellipsoidal set



First heuristics

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Chosen model of uncertainty





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Chosen model of uncertainty

Absolute robust decision	Robust deviation decision	Relative robust decision
Uncertainty sets		
Discrete set	Interval set	Ellipsoidal set



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Chosen model of uncertainty

Different definitions of worst case based approaches



· Avoid the pessimism of general robust min-max optimization



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Chosen model of uncertainty

Absolute robust decision	Robust deviation decision	Relative robust decision
Uncertainty sets		
Discrete set	Interval set	Ellipsoidal set



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Chosen problem to solve

General problems:

 $\min_{x\in X_d}f(x,d)$



First heuristics

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Chosen problem to solve

General problems:

 $\min_{x\in X_d}f(x,d)$

Consider binary linear problems with uncertainty in cost

$$\min_{x \in X} c^T x, \quad X = \{x \in \{0, 1\}^m; Ax = b\}$$



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Conclusions and perspectives

Chosen problem to solve

General problems:

 $\min_{x\in X_d}f(x,d)$

Consider binary linear problems with uncertainty in cost

$$\min_{x\in X} c^T x, \quad X = \{x \in \{0,1\}^m; Ax = b\}$$

Examples: Shortest path problem, k-median clustering problem, etc.



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Conclusions and perspectives

Complexity and existing methods

The absolute robust counterpart of binary linear problems under ellipsoidal uncertainty gives

$$\min_{x \in X} \max_{c \in U} c^T x \longrightarrow \min_{x \in X} \mu^T x + \sqrt{x^T \Sigma x} = \min_{x \in X} g(x)$$
(1)

[Ilyina 2017] $(\mu^T x + \Omega \sqrt{x^T \Sigma x} \rightarrow \mu^T x + \sqrt{x^T \Sigma x})$: replace Σ by $\Omega^2 \Sigma$)

Problem (1) is a binary non-linear problem \implies NP-hard



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Problem (1) is a binary non-linear problem \implies NP-hard

Methods to solve Problem (1)

Exact methods


First heuristics

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Complexity and existing methods

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Problem (1) is a binary non-linear problem \implies NP-hard

Methods to solve Problem (1)

Exact methods

- Writing (1) as a Binary Second Order Cone Program permits us to use existing exact solvers based on Branch-and-Bound methods (e.g., CPLEX)
- Research work about exact methods are proposed :
- [llyina *et al* 2017]
- [Buchheim et al. 2017]: A Frank-Wolfe based Branch-and-bound algorithm



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Complexity and existing methods

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Methods to solve Problem (1)

Exact methods Heuristic approaches



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Complexity and existing methods

The absolute robust counterpart of binary linear problems under ellipsoidal uncertainty gives

$$\min_{x \in X} \max_{c \in U} c^T x \longrightarrow \min_{x \in X} \mu^T x + \sqrt{x^T \Sigma x} = \min_{x \in X} g(x)$$
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Problem (1) is a binary non-linear problem \implies NP-hard

Methods to solve Problem (1)

Exact methods

Heuristic approaches

There is no proposition of a heuristic approach

Exact methods are not scalable

 \implies Proposition of a heuristics with the idea of adapting Frank-Wolfe, this time for a heuristics



First heuristics

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Conclusions and perspectives

Outline

1. Context and positioning

2. A Frank-Wolfe based heuristic approach applied on the robust shortest path problem

3. Another Frank-Wolfe based heuristic approach applied on the robust ${\tt k}\mbox{-median clustering problem}$

4. Conclusions and perspectives



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Outline

1. Context and positioning

2. A Frank-Wolfe based heuristic approach applied on the robust shortest path problem

3. Another Frank-Wolfe based heuristic approach applied on the robust k-median clustering problem

4. Conclusions and perspectives



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Conclusions and perspectives

Postitioning

Recall the positioning

Consider uncertainty in problems of the form

$$\min_{x \in X} c^{T} x, \quad X = \{x \in \{0, 1\}^{m}; Ax = b\}$$



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Postitioning

Recall the positioning

Consider uncertainty in problems of the form

$$\min_{x \in X} c^T x, \quad X = \{x \in \{0, 1\}^m; Ax = b\}$$

The absolute robust decision under ellipsoidal uncertainty gives

$$\min_{x \in X} \max_{c \in U} c^T x \quad \rightarrow \quad \min_{x \in X} \mu^T x + \sqrt{x^T \Sigma x}$$



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Postitioning

Recall the positioning

Consider uncertainty in problems of the form

$$\min_{x \in X} c^T x, \quad X = \{x \in \{0, 1\}^m; Ax = b\}$$

The absolute robust decision under ellipsoidal uncertainty gives

$$\min_{x \in X} \max_{c \in U} \mathbf{C}^T \mathbf{X} \quad \rightarrow \quad \min_{x \in X} \mu^T \mathbf{X} + \sqrt{\mathbf{X}^T \mathbf{\Sigma} \mathbf{X}}$$

The goal is to solve

$$\min_{x \in X} \mu^T x + \sqrt{x^T \Sigma x} = \min_{x \in X} g(x)$$
(2)



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Postitioning

Recall the positioning

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The absolute robust decision under ellipsoidal uncertainty gives

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🔷 The goal is to solve

$$\min_{x \in X} \mu^T x + \sqrt{x^T \Sigma x} = \min_{x \in X} g(x)$$
(2)

Since, the work is based on Frank-Wolfe, recall first the classical Frank-Wolfe algorithm



First heuristics

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Conclusions and perspectives

The classical Frank-Wolfe algorithm

f convex, continuously differentiable defined on a compact convex *D*. Consider convex optimization problems of the form

 $\min_{x\in D}f(x)$

Frank-Wolfe algorithm

Let $x^{(0)} \in D$ for k = 0 to K do compute $s^{(k)} := \underset{s \in D}{\operatorname{argmin}} \nabla f(x^{(k)})^T s$ update $x^{(k+1)} := (1 - \gamma^{(k)})x^{(k)} + \gamma^{(k)}s^{(k)}$ end for



[Jaggi 2013



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The classical Frank-Wolfe algorithm

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Frank-Wolfe algorithm Let $x^{(0)} \in D$

Let $x^{(k)} \in D$ for k = 0 to K do compute $s^{(k)} := \underset{s \in D}{\operatorname{argmin}} \nabla f(x^{(k)})^T s$ update $x^{(k+1)} := (1 - \gamma^{(k)})x^{(k)} + \gamma^{(k)}s^{(k)}$ end for



[Jaggi 2013

$$s^{(k)} = \underset{s \in D}{\operatorname{argmin}} [f(x^{(k)}) + \nabla f(x^{(k)})^{\mathsf{T}} (s - x^{(k)})] = \underset{s \in D}{\operatorname{argmin}} \nabla f(x^{(k)})^{\mathsf{T}} s$$



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Frank-Wolfe algorithm Let $x^{(0)} \in D$ for k = 0 to K do compute $s^{(k)} := \underset{s \in D}{\operatorname{argmin}} \nabla f(x^{(k)})^T s$ update $x^{(k+1)} := (1 - \gamma^{(k)})x^{(k)} + \gamma^{(k)}s^{(k)}$





Step-size

•
$$\gamma^{(k)} = \frac{2}{k+2}$$

• $\gamma^{(k)} = \operatorname*{argmin}_{\alpha \in [0,1]} f((1-\alpha)x^{(k)} + \alpha s^{(k)})$ (line search step)



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The classical Frank-Wolfe algorithm

f convex, continuously differentiable defined on a compact convex *D*. Consider convex optimization problems of the form

 $\min_{x\in D}f(x)$





Limits: Assumptions of Frank-Wolfe are not valid in our case



end for

First heuristics

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The classical Frank-Wolfe algorithm

f convex, continuously differentiable defined on a compact convex *D*. Consider convex optimization problems of the form

 $\min_{x\in D}f(x)$



Let $x^{(0)} \in D$ for k = 0 to K do compute $s^{(k)} := \underset{s \in D}{\operatorname{argmin}} \nabla f(x^{(k)})^T s$ update $x^{(k+1)} := (1 - \gamma^{(k)})x^{(k)} + \gamma^{(k)}s^{(k)}$ end for f f(x) f(x) Liansi 00121

Limits: Assumptions of Frank-Wolfe are not valid in our case
 Need for an adapted algorithm



First heuristics

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Conclusions and perspectives

The proposed approach

The idea behind Use classical Frank-Wolfe to solve

 $\min_{x \in \mathsf{Conv}(X)} \mu^T x + \sqrt{x^T \Sigma x}$

 $X = \{x \in \{0, 1\}^m; Ax = b\}$ Conv(X) = $\{x \in [0, 1]^m; Ax = b\}$



First heuristics

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The proposed approach

The idea behind Use classical Frank-Wolfe to solve

 $\min_{x \in \text{Conv}(X)} \mu^T x + \sqrt{x^T \Sigma x}$ $\{0, 1\}^m; Ax = b\}$

$$X = \{x \in \{0, 1\}^{m}; Ax = b\}$$

Conv(X) = $\{x \in [0, 1]^{m}; Ax = b\}$
The solution is not feasible



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The idea behind Use classical Frank-Wolfe to solve

 $\min_{x \in \mathsf{Conv}(X)} \mu^T x + \sqrt{x^T \Sigma x}$

$$X = \{x \in \{0, 1\}^m; Ax = b\}$$

Conv(X) = $\{x \in [0, 1]^m; Ax = b\}$
The solution is not feasible
The gradient is not well defined in zero



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 $\min_{x \in \mathsf{Conv}(X)} \mu^T x + \sqrt{x^T \Sigma x}$

$$X = \{x \in \{0, 1\}^m; Ax = b\}$$

Conv(X) = $\{x \in [0, 1]^m; Ax = b\}$
The solution is not feasible
The gradient is not well defined in zero

Before proceeding, some assumptions are needed



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First some assumptions

Three assumptions are necessary to our approach

(A1) For any real-valued vector a, there exists an efficient algorithm to solve $\min_{x \in X} a^T x$

(A2) For any real-valued vector a, there exists a solution for $\min_{x \in Conv(X)} a^T x$ that belongs to X

(A3) $0_{\mathbb{R}^m}$ does not belong to X

Recall X, Conv(X)

$$X = \{x \in \{0, 1\}^m; Ax = b\}$$

Conv(X) = $\{x \in [0, 1]^m; Ax = b\}$



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First some assumptions

Three assumptions are necessary to our approach

(A1) For any real-valued vector a, there exists an efficient algorithm to solve $\min_{x \in X} a^T x$

(A2) For any real-valued vector a, there exists a solution for $\min_{x \in Conv(X)} a^T x$ that belongs to X

(A3) $0_{\mathbb{R}^m}$ does not belong to X

Recall X, Conv(X)

$$X = \{x \in \{0, 1\}^m; Ax = b\}$$

Conv $(X) = \{x \in [0, 1]^m; Ax = b\}$

Thanks to (A3), for all $x \in X$, the gradient of g is well defined

$$\nabla g(x) = \mu + \frac{\Sigma x}{\sqrt{x^T \Sigma x}}$$



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The idea behind Use classical Frank-Wolfe to solve

$$\min_{x \in \mathsf{Conv}(X)} \mu^T x + \sqrt{x^T \Sigma x}$$



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The idea behind Use classical Frank-Wolfe to solve

 $\min_{x \in \mathsf{Conv}(X)} \mu^T x + \sqrt{x^T \Sigma x}$

Consider the best intermediate solution, that is feasible thanks to the assumptions.



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The proposed approach

```
DFW: a Frank-Wolfe based algorithm to solve
(2)
 1: x^{(0)} a random feasible solution, \varepsilon > 0 close to zero, K
     a maximum number of iterations.
 2: k \leftarrow 1
 3: stop \leftarrow false
 4: while k < K and \negstop do
         if g(x^{(k-1)}) - g(x^{(k)}) < \varepsilon: then
 5.
            stop \leftarrow true
 6:
 7.
        else
            s^{(k)} \in \operatorname{argmin} \nabla g(x^{(k)})^T y, with s^{(k)} \in X
 8:
                     y \in Conv(X)
            \gamma^{(k)} \leftarrow \operatorname{argmin} g(x^{(k)} + \alpha(s^{(k)} - x^{(k)}))
 g٠
                      \alpha \in [0,1]
            \mathbf{x}^{(k+1)} \leftarrow (1 - \gamma^{(k)}) \mathbf{x}^{(k)} + \gamma^{(k)} \mathbf{s}^{(k)}
10.
11:
        end if
12.
        k + +
13. end while
14: return
                    argmin
                                     g(s)
               s \in \{s^{(1)}, \dots, s^{(k-1)}\}
```



femto-st

TECHNOLOGIES

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The proposed approach

DFW: a Frank-Wolfe based algorithm to solve
(2)
1:
$$x^{(0)}$$
 a random feasible solution, $\varepsilon > 0$ close to zero, K
a maximum number of iterations.
2: $k \leftarrow 1$
3: stop \leftarrow false
4: while $k \leq K$ and \neg stop do
5: if $g(x^{(k-1)}) - g(x^{(k)}) < \varepsilon$: then
6: stop \leftarrow true
7: else
8: $s^{(k)} \in \underset{\substack{v \in Con(X) \\ v \in Con(X)}}{s \in [0,1]} \nabla g(x^{(k)})^T y$, with $s^{(k)} \in X$
9: $\gamma^{(k)} \leftarrow \underset{\alpha \in [0,1]}{\operatorname{argmin}} g(x^{(k)} + \alpha(s^{(k)} - x^{(k)}))$
10: $x^{(k+1)} \leftarrow (1 - \gamma^{(k)})x^{(k)} + \gamma^{(k)}s^{(k)}$
11: end if
12: $k + +$
13: end while
14: return $\underset{s \in \{s^{(1)}, \dots, s^{(k-1)}\}}{\operatorname{argmin}} g(s)$

- *s*^(*k*) minimum linear approximation
- $s^{(k)} \in X$ thanks to Assumption (A2)

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DFW: a Frank-Wolfe based algorithm to solve
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- $s^{(k)} \in X$ thanks to Assumption (A2)
- Line search step: minimize $g(x^{(k+1)})$



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8: $s^{(k)} \in \underset{\substack{\varphi \in \text{Conv}(X)}{\text{solution}} \nabla g(x^{(k)})^T y$, with $s^{(k)} \in X$
9: $\gamma^{(k)} \leftarrow \underset{\substack{\alpha \in [0,1]}{\alpha \in [0,1]}}{\text{solution}} \gamma^{(k)} + \alpha(s^{(k)} - x^{(k)}))$
10: $x^{(k+1)} \leftarrow (1 - \gamma^{(k)})x^{(k)} + \gamma^{(k)}s^{(k)}$
11: end if
12: $k + +$
13: end while
14: return $\underset{s \in \{s^{(1)}, \dots, s^{(k-1)}\}}{\text{solution}} g(s)$



- $s^{(k)} \in X$ thanks to Assumption (A2)
- Line search step: minimize $g(x^{(k+1)})$
- x^(k) converges in Conv(X)



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11: end if
12: $k + +$
13: end while
14: return $\underset{s \in \{s^{(1)}, \dots, s^{(k-1)}\}}{\operatorname{argmin}} g(s)$



- *s*^(*k*) minimum linear approximation
- $s^{(k)} \in X$ thanks to Assumption (A2)
- Line search step: minimize $g(x^{(k+1)})$
- x^(k) converges in Conv(X)
- We look at *s*^(*k*): return the best one of all the iterations

First heuristics

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Conclusions and perspectives

Numerical setup



Berlin Mitte-Center graph with 398 nodes and 871 edges with an illustration of a path from node 1 to node 294



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Numerical setup

Undirected grid graph $L \times L$, source node: 1, destination node L^2



Grid graph 6 \times 6 with 36 nodes and 60 edges



Grid graph 34×34 with 1156 nodes and 2244 edges



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Second heuristics

Conclusions and perspectives

Numerical setup

Setup

- The robust shortest path problem from node 1 to node L²
- $\Omega = 1$, (μ, Σ, x_0) random



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Conclusions and perspectives

Numerical results: behavior of the algorithm for L = 34

Denote, at each iteration k, the best solution so far as $s_{opt}^{(k)} = \operatorname{argmin}_{s^{(l)} \in \{s^{(1)}, \dots, s^{(k)}\}} g(s^{(l)})$





First heuristics

Second heuristics

Conclusions and perspectives

Numerical results

Results

• Change size of the graph



First heuristics

Second heuristics

Conclusions and perspectives

Numerical results

- Change size of the graph
- Compare with the solutions provided by CPLEX



First heuristics

Second heuristics

Conclusions and perspectives

Numerical results

- Change size of the graph
- Compare with the solutions provided by CPLEX
- For small to medium graphs, DFW gives the same solution as CPLEX



First heuristics

Second heuristics

Conclusions and perspectives

Numerical results

- Change size of the graph
- Compare with the solutions provided by CPLEX
- For small to medium graphs, DFW gives the same solution as CPLEX
- $L \ge 40$, branch-and-bound no more efficient



First heuristics

Second heuristics

Conclusions and perspectives

Numerical results

- Change size of the graph
- Compare with the solutions provided by CPLEX
- For small to medium graphs, DFW gives the same solution as CPLEX
- $L \ge 40$, branch-and-bound no more efficient
- L = 46, CPLEX stops after 2 hours and a half


First heuristics

Second heuristics

Conclusions and perspectives

Numerical results

Results

- Change size of the graph
- Compare with the solutions provided by CPLEX
- For small to medium graphs, DFW gives the same solution as CPLEX
- $L \ge 40$, branch-and-bound no more efficient
- *L* = 46, CPLEX stops after 2 hours and a half 200 iterations of DFW takes half an hour



First heuristics

Second heuristics

Conclusions and perspectives

Numerical results

Results

- Change size of the graph
- Compare with the solutions provided by CPLEX
- For small to medium graphs, DFW gives the same solution as CPLEX
- $L \ge 40$, branch-and-bound no more efficient
- L = 46, CPLEX stops after 2 hours and a half 200 iterations of DFW takes half an hour Same solution as best integer of CPLEX



First heuristics

Second heuristics

Conclusions and perspectives

Outline

1. Context and positioning

2. A Frank-Wolfe based heuristic approach applied on the robust shortest path problem

3. Another Frank-Wolfe based heuristic approach applied on the robust ${\tt k}\mbox{-median clustering problem}$

4. Conclusions and perspectives



First heuristics

Second heuristics

Conclusions and perspectives

The k-median clustering problem

Choose \Bbbk clusters to minimize the sum of the distances between the points and their cluster centers





First heuristics

Second heuristics

Conclusions and perspectives

The k-median clustering problem

Choose \Bbbk clusters to minimize the sum of the distances between the points and their cluster centers

$$\begin{split} \min_{z \in \mathbb{R}^{n \times n}} \sum_{i=1}^{n} \sum_{j=1}^{n} d(p_i, p_j) z_{ij} \\ \text{s.t.} \quad \sum_{i=1}^{n} z_{ij} = 1 \quad \forall j \in \{1, \dots, n\} \\ z_{ij} \leq y_i \quad \forall i, j \in \{1, \dots, n\}^2 \\ \sum_{i=1}^{n} y_i = k \\ z_{ij}, y_i \in \{0, 1\} \end{split}$$

In a matrix representation,

$$z_{ii} = y_i, i \in \{1,\ldots,n\}$$

$$y_i = 1 \implies p_i$$
 center

$$z_{ij} = 1 \implies p_j$$
 associated to center p_i



First heuristics

Second heuristics

Conclusions and perspectives

The k-median clustering problem

Choose \Bbbk clusters to minimize the sum of the distances between the points and their cluster centers

$$\begin{split} \min_{z \in \mathbb{R}^{n \times n}} \sum_{i=1}^{n} \sum_{j=1}^{n} d(p_i, p_j) z_{ij} \\ \text{s.t.} \quad \sum_{i=1}^{n} z_{ij} = 1 \quad \forall j \in \{1, \dots, n\} \\ z_{ij} \leq y_i \quad \forall i, j \in \{1, \dots, n\}^2 \\ \sum_{i=1}^{n} y_i = k \\ z_{ij}, y_i \in \{0, 1\} \end{split}$$

Constraint (C1):

Sum of each column = 1

Every point is associated to one and only cluster center



First heuristics

Second heuristics

Conclusions and perspectives

The k-median clustering problem

Choose \Bbbk clusters to minimize the sum of the distances between the points and their cluster centers

$$\begin{split} \min_{z \in \mathbb{R}^{n \times n}} \sum_{i=1}^{n} \sum_{j=1}^{n} d(p_i, p_j) z_{ij} \\ \text{s.t.} \quad \sum_{i=1}^{n} z_{ij} = 1 \quad \forall j \in \{1, \dots, n\} \\ z_{ij} \leq y_i \quad \forall i, j \in \{1, \dots, n\}^2 \\ \sum_{i=1}^{n} y_i = k \\ z_{ij}, y_i \in \{0, 1\} \end{split}$$

Constraint **(C2)**: Non-diagonal \leq diagonal If associate point to point \implies the second is a center



First heuristics

Second heuristics

Conclusions and perspectives

The k-median clustering problem

Choose \Bbbk clusters to minimize the sum of the distances between the points and their cluster centers

$$\min_{z \in \mathbb{R}^{n \times n}} \sum_{i=1}^{n} \sum_{j=1}^{n} d(p_i, p_j) z_{ij}$$

s.t.
$$\sum_{i=1}^{n} z_{ij} = 1 \quad \forall j \in \{1, \dots, n\}$$
$$z_{ij} \le y_i \quad \forall i, j \in \{1, \dots, n\}^2$$
$$\sum_{i=1}^{n} y_i = k$$
$$z_{ij}, y_i \in \{0, 1\}$$

Constraint (C3): Trace = kExactly k centers



First heuristics

Second heuristics

Conclusions and perspectives

Presence of uncertainty



If the distances are uncertain in the ${\bf k}\mbox{-median}$ clustering problem



First heuristics

Second heuristics

Conclusions and perspectives

Presence of uncertainty

If the distances are uncertain in the k-median clustering problem

Need for a robust solution



First heuristics

Second heuristics

Conclusions and perspectives

(3)

Presence of uncertainty

If the distances are uncertain in the k-median clustering problem
 Need for a robust solution

The k-median clustering problem can be written as

$$\min d^{T}z$$

s.t. $\sum_{i=1}^{n} Z_{n(i-1)+j} = 1 \quad \forall j \in \{1, \dots, n\}$
 $Z_{n(i-1)+j} \leq Z_{n(i-1)+i} \quad \forall i, j \in \{1, \dots, n\}^{2}$
 $\sum_{i=1}^{n} Z_{n(i-1)+i} = k$
 $z \in \{0, 1\}^{n^{2}}$



First heuristics

Second heuristics

Conclusions and perspectives

Presence of uncertainty

If the distances are uncertain in the k-median clustering problem

Need for a robust solution

The k-median clustering problem can be written as

$$\min d^{T}z$$
(3)
s.t. $\sum_{i=1}^{n} z_{n(i-1)+j} = 1 \quad \forall j \in \{1, \dots, n\}$
 $z_{n(i-1)+j} \leq z_{n(i-1)+i} \quad \forall i, j \in \{1, \dots, n\}^{2}$
 $\sum_{i=1}^{n} z_{n(i-1)+i} = k$
 $z \in \{0, 1\}^{n^{2}}$

- A flattening step
- A proof for equivalence of the definition of uncertainty between the two writings



First heuristics

Second heuristics

Conclusions and perspectives

Robust decision under ellipsoidal uncertainty

The absolute robust k-median clustering problem under ellipsoidal uncertainty is

$$\min_{z \in X} \mu^T z + \sqrt{z^T \Sigma z} \tag{4}$$

with

$$X = \{z \in \{0, 1\}^{n^2} \text{ s.t.} \\ \sum_{i=1}^n z_{n(i-1)+j} = 1 \quad \forall j \in \{1, \dots, n\}, \\ z_{n(i-1)+j} \le z_{n(i-1)+i} \forall i, j \in \{1, \dots, n\}^2, \\ \sum_{i=1}^n z_{n(i-1)+i} = k\}$$



First heuristics

Second heuristics

Conclusions and perspectives

Robust decision under ellipsoidal uncertainty

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First heuristics

Second heuristics

Conclusions and perspectives

Robust decision under ellipsoidal uncertainty

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This follows the formulation of our study

 Assumption (A2) not satisfied: no exact binarity relaxation
 cannot apply DFW



First heuristics

Second heuristics

Conclusions and perspectives

Robust decision under ellipsoidal uncertainty

The absolute robust k-median clustering problem under ellipsoidal uncertainty is

$$\min_{z \in X} \mu^T z + \sqrt{z^T \Sigma z} \tag{4}$$

with

$$X = \{z \in \{0, 1\}^{n^2} \text{ s.t.} \\ \sum_{i=1}^{n} z_{n(i-1)+j} = 1 \quad \forall j \in \{1, \dots, n\}, \\ z_{n(i-1)+j} \le z_{n(i-1)+i} \forall i, j \in \{1, \dots, n\}^2, \\ \sum_{i=1}^{n} z_{n(i-1)+i} = k\}$$

This follows the formulation of our study
 Assumption (A2) not satisfied: no exact binarity relaxation
 cannot apply DFW
 We propose another Frank-Wolfe based algorithm for the robust k-median clustering



First heuristics

Second heuristics

Conclusions and perspectives

The proposed approach

The idea behind Use classical Frank-Wolfe to solve

 $\min_{x \in \mathsf{Conv}(X)} \mu^T x + \sqrt{x^T \Sigma x}$



First heuristics

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Second heuristics

Conclusions and perspectives

The proposed approach

The idea behind Use classical Frank-Wolfe to solve

$$\min_{\in \text{Conv}(X)} \mu^T x + \sqrt{x^T \Sigma x}$$

$$Conv(X) = \{z \in [0, 1]^{n^2} \text{ s.t.} \\ \sum_{i=1}^{n} Z_{n(i-1)+j} = 1 \quad \forall j \in \{1, \dots, n\}, \\ Z_{n(i-1)+j} \le Z_{n(i-1)+i} \forall i, j \in \{1, \dots, n\}^2, \\ \sum_{i=1}^{n} Z_{n(i-1)+i} = k\}$$

Conv(X): Constraints (C1), (C2), (C3) satisfied, variables not binary



First heuristics

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Second heuristics

Conclusions and perspectives

The proposed approach

The idea behind Use classical Frank-Wolfe to solve

$$\min_{\in \mathsf{Conv}(X)} \mu^T x + \sqrt{x^T \Sigma x}$$

$$Conv(X) = \{z \in [0, 1]^{n^2} \text{ s.t.} \\ \sum_{i=1}^{n} Z_{n(i-1)+j} = 1 \quad \forall j \in \{1, \dots, n\}, \\ Z_{n(i-1)+j} \le Z_{n(i-1)+i} \forall i, j \in \{1, \dots, n\}^2, \\ \sum_{i=1}^{n} Z_{n(i-1)+i} = k\}$$

Conv(X): Constraints (C1), (C2), (C3) satisfied, variables not binary Consider the feasible round of the mean of all the intermediate solutions.



First heuristics

Second heuristics

Conclusions and perspectives

The proposed approach

MFW: a Frank-Wolfe based algorithm to solve Problem $\left(4\right)$

1: $x^{(0)} \in \text{Conv}(X)$ a random solution, $\varepsilon > 0$ close to zero, K a maximum number of iterations. 2: $\mathring{k} \leftarrow 1$ 3: stop \leftarrow false 4: while $\dot{k} < \dot{K}$ and \neg stop do if $q(x^{(\hat{k}-1)}) - q(x^{(\hat{k})}) < \varepsilon$: then 5: stop \leftarrow true 6: else 7: $s^{(\hat{k})} \in \operatorname{argmin} \nabla g(x^{(\hat{k})})^T y$ 8: $y \in Conv(X)$ $\gamma^{(\hat{k})} \leftarrow \operatorname{argmin} g(x^{(\hat{k})} + \alpha(s^{(\hat{k})} - x^{(\hat{k})}))$ 9: $\alpha \in [0,1]$ $\boldsymbol{x}^{(\hat{k}+1)} \leftarrow (1 - \gamma^{(\hat{k})}) \boldsymbol{x}^{(\hat{k})} + \gamma^{(\hat{k})} \boldsymbol{s}^{(\hat{k})}$ 10: end if 11: k + +12. 13: end while 14: return a feasible round of $\mu_{k-1} = \frac{\sum_{i=1}^{k-1} \mathbf{s}^{(i)}}{k}$



First heuristics

Second heuristics

Conclusions and perspectives

The proposed approach

MFW: a Frank-Wolfe based algorithm to solve Problem $\left(4\right)$

1: $x^{(0)} \in \text{Conv}(X)$ a random solution, $\varepsilon > 0$ close to zero, \mathring{K} a maximum number of iterations.

- 2: *k* ← 1
- $\textbf{3: stop} \leftarrow \textbf{false}$
- 4: while $\mathring{k} \leq \mathring{K}$ and \neg stop **do**

5: if
$$g(x^{(\hat{k}-1)}) - g(x^{(\hat{k})}) < \varepsilon$$
: then

- 6: $stop \leftarrow true$
- 7: else

8:
$$s^{(k)} \in \underset{y \in \text{Conv}(X)}{\operatorname{argmin}} \nabla g(x^{(k)})^T y$$

9:
$$\gamma^{(\hat{k})} \leftarrow \underset{\alpha \in [0,1]}{\operatorname{argmin}} g(x^{(\hat{k})} + \alpha(s^{(\hat{k})} - x^{(\hat{k})}))$$

10:
$$x^{(\hat{k}+1)} \leftarrow (1 - \gamma^{(\hat{k})}) x^{(\hat{k})} + \gamma^{(\hat{k})} s^{(\hat{k})}$$

- 11: end if
- 12: *k*++
- 13: end while

14: return a feasible round of
$$\mu_{k-1} = \frac{\sum_{i=1}^{k-1} s^{(i)}}{k-1}$$



• $s^{(k)} \notin X \implies$ need to round



First heuristics

Second heuristics

Conclusions and perspectives

The proposed approach

MFW: a Frank-Wolfe based algorithm to solve Problem $\left(4\right)$

- 1: $x^{(0)} \in \text{Conv}(X)$ a random solution, $\varepsilon > 0$ close to zero, \mathring{K} a maximum number of iterations. 2: $\mathring{k} \leftarrow 1$ 3: stop \leftarrow false 4: while $\mathring{k} \leq \mathring{K}$ and \neg stop do 5: if $g(x^{(\check{k}-1)}) - g(x^{(\check{k})}) < \varepsilon$: then 6: stop \leftarrow true 7: else 8: $s^{(\check{k})} \in \operatorname{argmin} \nabla g(x^{(\check{k})})^T y$
- 9: $\gamma^{(\hat{k})} \leftarrow \underset{\alpha \in [0,1]}{\operatorname{argmin}} g(x^{(\hat{k})} + \alpha(s^{(\hat{k})} x^{(\hat{k})}))$
- 10: $x^{(\hat{k}+1)} \leftarrow (1-\gamma^{(\hat{k})})x^{(\hat{k})} + \gamma^{(\hat{k})}s^{(\hat{k})}$
- 11: end if
- 12: *k*++
- 13: end while
- 14: return a feasible round of $\mu_{\vec{k}-1} = \frac{\sum_{i=1}^{k-1} s^{(i)}}{\vec{k}-1}$



- $s^{(k)} \notin X \implies$ need to round
- Line search step: minimize $g(x^{(k+1)})$



First heuristics

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Second heuristics 0000000000

Conclusions and perspectives

The proposed approach

MFW: a Frank-Wolfe based algorithm to solve Problem (4)

- 1: $x^{(0)} \in \text{Conv}(X)$ a random solution, $\varepsilon > 0$ close to zero, \mathring{K} a maximum number of iterations. 2: $\mathring{k} \leftarrow 1$ 3: stop \leftarrow false 4: while $\dot{k} \leq \dot{K}$ and \neg stop **do** if $q(x^{(k-1)}) - q(x^{(k)}) < \varepsilon$: then 5:
- 6: stop \leftarrow true
- else 7:

8:
$$\mathbf{s}^{(k)} \in \underset{y \in \text{Conv}(X)}{\operatorname{argmin}} \nabla g(\mathbf{x}^{(k)})^T \mathbf{y}$$

9: $\gamma^{(\hat{k})} \leftarrow \underset{x \in \text{argmin}}{\operatorname{argmin}} g(\mathbf{x}^{(\hat{k})} + \alpha(\mathbf{s}^{(\hat{k})} - \mathbf{x}^{(\hat{k})}))$

9:
$$\gamma^{(k)} \leftarrow \underset{\alpha \in [0,1]}{\operatorname{argmin}} g(X^{(k)} + \alpha(S^{(k)} - X^{(k)})$$

0: $X^{(k+1)} \leftarrow (1 - \gamma^{(k)}) X^{(k)} + \gamma^{(k)} S^{(k)}$

- 10:
- end if 11:
- k + +12.
- 13: end while

14: return a feasible round of
$$\mu_{k-1} = rac{\sum_{i=1}^{k-1} s^{(i)}}{k-1}$$



- $s^{(k)} \notin X \implies$ need to round
- Line search step: minimize $g(x^{(k+1)})$
- $x^{(k)}$ converges in Conv(X)



First heuristics

Second heuristics

Conclusions and perspectives

The proposed approach

MFW: a Frank-Wolfe based algorithm to solve Problem $\left(4\right)$

- 1: $x^{(0)} \in \text{Conv}(X)$ a random solution, $\varepsilon > 0$ close to zero, \mathring{K} a maximum number of iterations. 2: $\mathring{k} \leftarrow 1$
- $\textbf{3: stop} \leftarrow \textbf{false}$
- 4: while $\mathring{k} \leq \mathring{K}$ and \neg stop **do**
- 5: if $g(x^{(\hat{k}-1)}) g(x^{(\hat{k})}) < \varepsilon$: then
- 6: $stop \leftarrow true$
- 7: else

8:
$$s^{(k)} \in \underset{y \in \text{Conv}(X)}{\operatorname{argmin}} \nabla g(x^{(k)})^T y$$

9:
$$\gamma^{(\hat{k})} \leftarrow \underset{\alpha \in [0,1]}{\operatorname{argmin}} g(x^{(\hat{k})} + \alpha(s^{(\hat{k})} - x^{(\hat{k})})$$

- 10: $x^{(\tilde{k}+1)} \leftarrow (1 \gamma^{(\tilde{k})}) x^{(\tilde{k})} + \gamma^{(\tilde{k})} s^{(\tilde{k})}$
- 11: end if
- 12: *k*++
- 13: end while
- 14: return a feasible round of $\mu_{\hat{k}-1} = \frac{\sum_{i=1}^{\hat{k}-1} s^{(i)}}{\hat{k}-1}$



- $s^{(k)} \notin X \implies$ need to round
- Line search step: minimize $g(x^{(k+1)})$
- x^(k) converges in Conv(X)
- We look at *s*^(*k*): return the feasible round of the mean of all the iterations



Context ar	nd	positioning
000000	0	0

Second heuristics

Conclusions and perspectives

A feasible rounding algorithm: example of a 2-median clustering with 10 points

Γ	0.53	0	0.53	0	0	0	0	0.05	0	0.53
	0	0.14	0.14	0.14	0.02	0	0.14	0.14	0	0
l	0	0	0	0	0	0	0	0	0	0
	0	0.39	0	0.38	0.38	0.38	0	0	0.32	0.25
	0	0	0	0.09	0.09	0.09	0.09	0	0	0.09
	0	0	0	0.04	0.04	0.04	0	0	0.04	0
	0	0	0	0	0	0	0	0	0	0
	0.47	0.47	0.01	0	0.46	0.14	0.43	0.47	0.3	0.13
ł	0	0	0.32	0.34	0	0.34	0.34	0.34	0.34	0
L	0	0	0	0	0	0	0	0	0	0



Context a	nd	positioning
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Second heuristics

Conclusions and perspectives

A feasible rounding algorithm: example of a 2-median clustering with 10 points

۲ 0	.53	0	0.53	0	0	0	0	0.05	0	0.53	1	۲ 1							0		-	1
	0	0.14	0.14	0.14	0.02	0	0.14	0.14	0	0		0	0						0			
	0	0	0	0	0	0	0	0	0	0		0		0					0			
	0	0.39	0	0.38	0.38	0.38	0	0	0.32	0.25		0			0				0			
	0	0	0	0.09	0.09	0.09	0.09	0	0	0.09		0				0			0			
	0	0	0	0.04	0.04	0.04	0	0	0.04	0	$ \rightarrow$	0					0		0			
	0	0	0	0	0	0	0	0	0	0		0						0	0			
0	.47	0.47	0.01	0	0.46	0.14	0.43	0.47	0.3	0.13		0							1			
	0	0	0.32	0.34	0	0.34	0.34	0.34	0.34	0		0							0	0		
L	0	0	0	0	0	0	0	0	0	0		LΟ							0		0	

Sort the diagonal elements, and choose the 2 biggest elements



Context and	positioning
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Second heuristics

Conclusions and perspectives

A feasible rounding algorithm: example of a 2-median clustering with 10 points

Γ	0.53	0	0.53	0	0	0	0	0.05	0	0.53	1	۲ 1	0	1	0	0	0	0	0	0	17	I
	0	0.14	0.14	0.14	0.02	0	0.14	0.14	0	0		0	0						0			İ
	0	0	0	0	0	0	0	0	0	0	1	0		0					0			ĺ
	0	0.39	0	0.38	0.38	0.38	0	0	0.32	0.25		0			0				0			ĺ
	0	0	0	0.09	0.09	0.09	0.09	0	0	0.09		0				0			0		1	ĺ
	0	0	0	0.04	0.04	0.04	0	0	0.04	0	$ \rightarrow$	0					0		0		ļ	ĺ
	0	0	0	0	0	0	0	0	0	0	ļ	0						0	0		ļ	ĺ
	0.47	0.47	0.01	0	0.46	0.14	0.43	0.47	0.3	0.13		0	1	0	1	1	1	1	1	1	0	ĺ
	0	0	0.32	0.34	0	0.34	0.34	0.34	0.34	0		0							0	0		ĺ
L	0	0	0	0	0	0	0	0	0	0]	LΟ							0		0	l

Sort the diagonal elements, and choose the 2 biggest elements

In reduced matrix, sort each column



Context and	l positioning
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Second heuristics

Conclusions and perspectives

A feasible rounding algorithm: example of a 2-median clustering with 10 points

Γ Ο	.53	0	0.53	0	0	0	0	0.05	0	0.53 -	1	Γ1	0	1	0	0	0	0	0	0	1]
	0	0.14	0.14	0.14	0.02	0	0.14	0.14	0	0		0	0	0	0	0	0	0	0	0	0
	0	0	0	0	0	0	0	0	0	0		0	0	0	0	0	0	0	0	0	0
	0	0.39	0	0.38	0.38	0.38	0	0	0.32	0.25		0	0	0	0	0	0	0	0	0	0
	0	0	0	0.09	0.09	0.09	0.09	0	0	0.09		0	0	0	0	0	0	0	0	0	0
	0	0	0	0.04	0.04	0.04	0	0	0.04	0		0	0	0	0	0	0	0	0	0	0
	0	0	0	0	0	0	0	0	0	0		0	0	0	0	0	0	0	0	0	0
0	.47	0.47	0.01	0	0.46	0.14	0.43	0.47	0.3	0.13		0	1	0	1	1	1	1	1	1	0
	0	0	0.32	0.34	0	0.34	0.34	0.34	0.34	0		0	0	0	0	0	0	0	0	0	0
L	0	0	0	0	0	0	0	0	0	0		0	0	0	0	0	0	0	0	0	0

Sort the diagonal elements, and choose the 2 biggest elements

In reduced matrix, sort each column

Then the rest equals zero, and the rounding is done!



First heuristics

Second heuristics

Conclusions and perspectives

Numerical setup

Setup

- We changed the number of points *n* for the *k*-median problem for k = 2
- We compared with the solutions provided by CPLEX
- $\Omega = 1$, and for every *n*, 80 different (μ , Σ , x_0)



First heuristics

Second heuristics

Conclusions and perspectives

Numerical results of MFW Algorithm

$$E_r = \frac{g(\hat{x}) - p^*}{p^*} \qquad \#\{E_r = 0\}$$

n	Time(s) of CPLEX	Time(s) MFW	$\#\{E_r=0\}$	<u>E</u> r
5	0.1644	5.0149	55 %	0.0555
6	0.5424	7.8	71.25 %	0.0513
7	0.8296	12.9796	48.75 %	0.0486
8	0.9948	6.9707	67.5 %	0.0186
9	1.9202	9.6168	63.75 %	0.0246
10	2.1028	16.6282	58.75 %	0.0432
11	2.1607	14.1045	70 %	0.0447
12	3.6378	19.778	23 %	0.0862
13	4.1873	17.8977	35 %	0.0694



First heuristics

Second heuristics

Conclusions and perspectives

Numerical results of MFW Algorithm

$$E_r = \frac{g(\hat{x}) - p^*}{p^*} \qquad \#\{E_r = 0\}$$

n	Time(s) of	Time(s) MFW	$\#\{E_r=0\}$	<u>E</u> r
	CPLEX			
5	0.1644	5.0149	55 %	0.0555
6	0.5424	7.8	71.25 %	0.0513
7	0.8296	12.9796	48.75 %	0.0486
8	0.9948	6.9707	67.5 %	0.0186
9	1.9202	9.6168	63.75 %	0.0246
10	2.1028	16.6282	58.75 %	0.0432
11	2.1607	14.1045	70 %	0.0447
12	3.6378	19.778	23 %	0.0862
13	4.1873	17.8977	35 %	0.0694



The relative error is in average small (0.0186 to 0.0862)



First heuristics

Second heuristics

Conclusions and perspectives

Numerical results of MFW Algorithm

$$E_r = \frac{g(\hat{x}) - p^*}{p^*} \qquad \#\{E_r = 0\}$$

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The relative error equals zero in up to 70% of the cases



First heuristics

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Conclusions and perspectives

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CPLEX is faster but the difference in time between MFW Algorithm and CPLEX is not very big (around 1/5 in average)



First heuristics

Second heuristics

Conclusions and perspectives

Outline

1. Context and positioning

2. A Frank-Wolfe based heuristic approach applied on the robust shortest path problem

3. Another Frank-Wolfe based heuristic approach applied on the robust k-median clustering problem

4. Conclusions and perspectives



First heuristics

Second heuristics

Conclusions and perspectives

Conclusion

· Considering the uncertainty in optimization problems is important



First heuristics

Second heuristics

Conclusions and perspectives

Conclusion

- Considering the uncertainty in optimization problems is important
- The robust problem with an ellipsoidal uncertainty of a binary linear problem in the cost function is a hard problem


First heuristics

Second heuristics

Conclusions and perspectives

- Considering the uncertainty in optimization problems is important
- The robust problem with an ellipsoidal uncertainty of a binary linear problem in the cost function is a hard problem
- We propose a heuristic approach based on Frank-Wolfe applied on the robust shortest path problem



First heuristics

Second heuristics

Conclusions and perspectives

- Considering the uncertainty in optimization problems is important
- The robust problem with an ellipsoidal uncertainty of a binary linear problem in the cost function is a hard problem
- We propose a heuristic approach based on Frank-Wolfe applied on the robust shortest path problem
- Numerical results show that the heuristic approach gives the optimal solution



First heuristics

Second heuristics

Conclusions and perspectives

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- An extension on the robust k-median clustering has been studied



First heuristics

Second heuristics

Conclusions and perspectives

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- A heuristic algorithm based on Frank-Wolfe has been proposed, with a feasible rounding algorithm



First heuristics

Second heuristics

Conclusions and perspectives

- Considering the uncertainty in optimization problems is important
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- Numerical results show that the heuristic approach gives the optimal solution
- An extension on the robust k-median clustering has been studied
- A heuristic algorithm based on Frank-Wolfe has been proposed, with a feasible rounding algorithm
- Results show that this algorithm gives the optimal solution in most of the cases, and that it gives close-to-optimal solutions when they are not optimal



First heuristics

Second heuristics

Conclusions and perspectives

Perspectives

• DFW Algorithm could be improved (better results, less processing timefor example using the away step FW)



First heuristics

Second heuristics

Conclusions and perspectives

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- More numerical results could include a study of the algorithm's parameters, and more tests with larger instances



First heuristics

Second heuristics

Conclusions and perspectives

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First heuristics

Second heuristics

Conclusions and perspectives

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First heuristics

Second heuristics

Conclusions and perspectives

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- More numerical results could include a study of the algorithm's parameters, and more tests with larger instances
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- Improve MFW Algorithm (e.g., by improving the rounding technique)
- Test MFW with different uncertainty configurations of the clusters



First heuristics

Second heuristics

Conclusions and perspectives

Thank you for your attention

